

Adaptive interpolation of multidimensional signals for compression on board an aircraft

N I Glumov^{1,2}, M V Gashnikov^{1,2}

¹Samara National Research University, Moskovskoe Shosse 34A, Samara, Russia, 443086

²Image Processing Systems Institute of RAS - Branch of the FSRC "Crystallography and Photonics" RAS, Molodogvardejskaya street 151, Samara, Russia, 443001

e-mail: mgash@smr.ru

Abstract. We consider the compression of multidimensional signals on the aircraft board. We describe the data of such signals as a hypercube, which is "rotated" in a special way. To compress this hypercube, we use a hierarchical compression method. As one of the stages of this method, we use an adaptive interpolation algorithm. The adaptive algorithm automatically switches between different interpolating functions at each signal point. We perform computational experiments in real-world multidimensional signals. Computational experiments confirm that the use of proposed adaptive interpolator allows increasing (up to 31%) the compression ratio of the "rotated" hypercube corresponding to multidimensional hyperspectral signals.

1. Introduction

The growing interest in applied problems in the field of processing multidimensional signals [1-4] determines the relevance of research in this area. One of the main issues is the data size corresponding to the multi-dimensional signals. For example, data of hyperspectral remote sensing [1, 3], as one of the types of multidimensional signal, contain up to several hundred large-sized components of high bit depth. With airborne compression, this information needs to be transmitted through a limited communication channel. In this situation, the use of compression [5-8] is the only possible solution.

Currently, there are many methods of compression: wavelet [9], spectral [10], fractal [11], etc. However, all of them are very limited in airborne compression due to the high computational complexity and complexity of error control in the spatial domain. Besides, when a hyper-spectral data is received, a hypercube of a multidimensional signal is often "rotated" (see Figure 1-2) in a specific way: the first component (band) contains the first lines of the source bands; the second band includes the second lines, etc. We can see that this leads to the appearance of anisotropic correlation peculiarities in the signal cross-sections.

In the described conditions, the method of multidimensional signal compression based on hierarchical grid interpolation [12-13] has proven itself well. The most difficult stage of this compression method, which largely determines the efficiency of the method as a whole, is an interpolator of a multidimensional signal. In this paper, an adaptive interpolator based on hybrid technology is proposed for interpolation of specifically "rotated" multidimensional signals corresponding to hyperspectral remote sensing data. This technology combines the autoregressive

prediction of the signal cross-sections and adaptive parameterized interpolation within the cross-sections, which makes it possible to use the above-described correlation anisotropy of the multidimensional signal effectively.

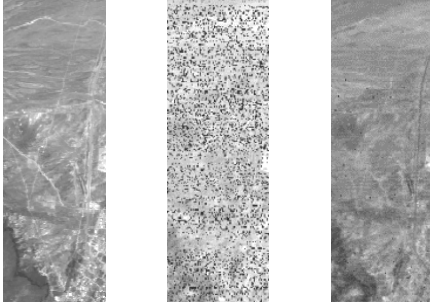


Figure 1. Cross-sections No. 10, 100, 120 of an “un-rotated” hyperspectral cube corresponding to the “natural” state of a multidimensional signal that can be processed and visualized in the data repository.

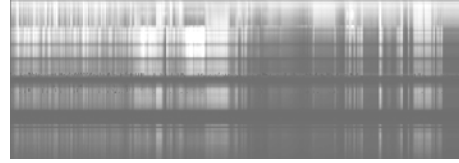


Figure 2. An example of a “rotated” cross-section of hyperspectral cube corresponding to a multidimensional signal compressed on board.

To study the proposed multidimensional interpolator, computational experiments are performed on natural multidimensional signals.

2. Autoregressive prediction of cross-sections of multidimensional signal

Consider a multidimensional (D -dimensional) signal

$$X = \{x(d_0, d_1, \dots, d_{D-1})\}. \quad (1)$$

This signal can also be considered as a set of $(D-1)$ dimensional cross-sections:

$$X^t = \{x^t(d_1, \dots, d_{D-1})\} = \{x(t, d_1, \dots, d_{D-1})\}, 0 \leq t < T. \quad (2)$$

Often these cross-sections are highly correlated (see Figures 1-2), for example, when processing hyperspectral data of remote sensing (for a hyperspectral signal of this type $D = 3$, and T coincides with the number of spectral bands). To account for the interdependency of the components, we use the linear autoregressive model:

$$P^t = k_1 X^{t-1} + k_2 X^{t-2} + \dots + k_N X^{t-N}, \quad (3)$$

where P is the predicted cross-section of the multidimensional signal X , k_i are regression coefficients, N is the number of reference cross-sections used for the prediction. These coefficients are found from the condition of minimizing the quadratic error between the original and predicted components:

$$\varepsilon_t^2 = E \left\{ \left(X^t - \sum_{i=1}^N k_i X^{t-i} \right)^2 \right\} \rightarrow \min_{\{k_i\}}. \quad (3)$$

Consider also the differential cross-section of the signal

$$R^t(d_1, \dots, d_{D-1}) = X^t(d_1, \dots, d_{D-1}) - P^t(d_1, \dots, d_{D-1}), 1 \leq t < T. \quad (4)$$

The variance of differential cross-section R^t is usually much smaller than the variance of the original cross-section X^t , and the probability distribution is much less uniform. Therefore, the differential cross-sections (4) are much more preferable for some types of processing, for example for compression.

3. Hierarchical compression of multidimensional signals

The difference cross-sections (4) are decorrelated, so that they can be processed independently. In this paper, these difference components are compressed using a hierarchical compression method [12–13], which uses a non-redundant hierarchical representation of a multidimensional signal $\mathbf{X} = \{x(\bar{d})\}$ as a set of L scale levels \mathbf{X}_l :

$$\mathbf{X} = \bigcup_{l=0}^{L-1} \mathbf{X}_l, \quad \mathbf{X}_l = \{x(\bar{d}) : \bar{d} \in I_l\}, \quad (5)$$

where I_l is the set of sample indices for scale level \mathbf{X}_l :

$$I_{L-1} = \{2^{L-1}\bar{d}\}, \quad I_l = \{2^l\bar{d}\} \setminus \{2^{l+1}\bar{d}\}, \quad 0 \leq l < L. \quad (6)$$

The scale level number $(L-1)$ is the resampled “grid” of signal samples with the step of $2^{(L-1)}$ along each of the coordinates, and any other level (number l) is the grid of samples with the step of 2^l , from which all samples with doubled step are excluded.

During compression, the scale levels are compressed sequentially in order of decreasing their numbers. At the same time, more resampled levels are interpolated based on samples of less resampled levels. Since peculiarities of post-interpolation residues are similar to peculiarities of differences (4), their coding is much more efficient than coding sources samples.

4. Adaptive interpolation of multidimensional signals during compression

The most critical step of hierarchical compression is the interpolator. In this work, differential cross-sections (4) are compressed. The dimension of these differential cross-sections is one less than the dimension of the original signal. Thus, for three-dimensional remote sensing, the interpolator will work with two-dimensional data. Therefore, further, to simplify the presentation, we describe a two-dimensional version of the adaptive interpolator.

To ensure low computational complexity of hierarchical compression, we often use trivial interpolation procedures, based on averaging over the nearest samples of more resampled scale levels. Here is an example of an interpolation procedure:

$$\hat{x}_l^{(1)}(2m+1, 2n+1) = \frac{1}{4}(\bar{x}_{l+1}(m, n) + \bar{x}_{l+1}(m+1, n) + \bar{x}_{l+1}(m, n+1) + \bar{x}_{l+1}(m+1, n+1)), \quad (7)$$

where $\bar{x}_{l+1}(m, n)$ are samples of a more resampled scale level, which have already passed compression and decompression.

This scheme is straightforward, but does not take into account local signal characteristics, for example, the oblong structures of onboard remote sensing data [14-16] (see Figure 2). Therefore, in this work, an adaptive interpolator is used to compress such remote sensing data. Besides function (7) this adaptive interpolator, uses two more interpolating functions that increase interpolation accuracy of oblong structures by averaging “along” them

$$\hat{x}_l^{(0)}(2m+1, 2n+1) = \frac{1}{2}(\bar{x}_{l+1}(m, n) + \bar{x}_{l+1}(m+1, n+1)) \quad (8)$$

$$\hat{x}_l^{(2)}(2m+1, 2n+1) = \frac{1}{2}(\bar{x}_{l+1}(m+1, n) + \bar{x}_{l+1}(m, n+1)) \quad (9)$$

The choice of the interpolating function for each signal sample is carried out by the parameterized decision rule:

$$\hat{x}_l(m, n) = \hat{x}_l^{(j)}(m, n), \quad j = \begin{cases} 0, & \mu_l(m, n) < \alpha; \\ 1, & \alpha \leq \mu_l(m, n) \leq \beta; \\ 2, & \mu_l(m, n) > \beta; \end{cases}$$

where α, β are parameters of the decision rule (thresholds for switching between interpolating functions). These parameters are calculated automatically based on minimization of interpolation error or entropy of quantized post-interpolation residues; $\mu_l(m, n)$ is a feature describing the magnitude and direction of the elongated structure in the local neighborhood of the current signal sample:

$$\mu_l(2m+1, 2n+1) = |\bar{x}_{l+1}(m, n) - \bar{x}_{l+1}(m+1, n+1)| - |\bar{x}_{l+1}(m, n+1) - \bar{x}_{l+1}(m+1, n)|. \quad (10)$$

The large absolute values $|\mu_l(2m+1, 2n+1)|$ of the feature (10) describe to the samples corresponding the stable oblong structures. In these situations, interpolation (8-9) “along” these

structures is preferred. Small values of the attribute (10) correspond to the signal samples located in relatively uniform signal areas. In these areas, the “averaging” interpolation (7) works more precisely by averaging a noise.

The optimization of the adaptive interpolator according to the parameters α , β is performed separately [17] for each signal realization (more precisely, separately for each hierarchical signal level).

5. Experimental study of the adaptive interpolator

The proposed hybrid interpolator, including an intercomponent approximator and an intracomponent adaptive interpolator, was implemented by software and built into the hierarchical compression method. Based on this software, we performed an experimental study of the proposed interpolator effectiveness in nature multidimensional signal sets, “rotated” in a specific way to airborne compression (see the example in Figure 2). We used the following signal sets:

- signals [14] of hyper-spectrometer AVIRIS (224 bands);
- signals [15] of «TokyoTech» hyperspectral dataset (31 bands);
- signals [16] of hyper-spectrometer SpecTIR (360 bands, see Figure 1).

As a measure of the proposed interpolator efficiency, we used the gain G in the archive size (in %), which was provided by replacing the averaging interpolator (7) with the proposed hybrid interpolator in the frame of hierarchical compression method:

$$G = 100\% \cdot (S_{new} - S_{base}) / S_{base} , \quad (11)$$

where S_{base} , S_{new} are the archive sizes when using averaging and proposed interpolators, respectively.

We estimated the dependence of gain (11) on the quadratic error ε^2 introduced during compression. Typical results are shown in Tables 1-9. We can see that the proposed hybrid interpolator provides a noticeable gain (up to 31%) for the averaging interpolator.

Table 1. The gain of the adaptive interpolator for the averaging interpolator in the test signal “Agriculture & Vegetation” of SpecTIR hyper-spectrometer.

ε^2	0.00	0.67	2.00	9.80	33.74	118.02	249.83
$G, \%$	5.74	7.57	8.45	9.69	11.44	10.36	9.07

Table 2. The gain of the adaptive interpolator for the averaging interpolator in the test signal “Cuprite” of AVIRIS hyper-spectrometer.

ε^2	0.00	0.66	1.99	9.81	34.82	126.82	271.50
$G, \%$	13.09	17.95	20.98	24.95	25.05	22.72	19.67

Table 3. The gain of the adaptive interpolator for the averaging interpolator in the test signal “Cloth-2” of “TokyoTech” hyperspectral dataset.

ε^2	0.00	36.23	813.24	3068.88	6470.68	10730.59	15513.49
$G, \%$	5.22	9.94	13.96	3.43	-3.16	-6.81	-9.16

Table 4. The gain of the adaptive interpolator for the averaging interpolator in the test signal “Gulf of Mexico Wetland” of SpecTIR hyper-spectrometer.

ε^2	0.00	0.67	1.99	9.52	31.98	111.70	232.48
$G, \%$	5.22	6.84	7.67	8.84	8.67	5.76	2.83

Table 5. The gain of the adaptive interpolator for the averaging interpolator in the test signal “Doll” of “TokyoTech” hyperspectral dataset.

ε^2	0.00	36.20	780.62	2874.67	6064.38	10200.76	15172.86
$G, \%$	8.87	13.93	5.22	0.19	-2.49	-4.21	-5.49

Table 6. The gain of the adaptive interpolator for the averaging interpolator in the test signal “Low Altitude” of AVIRIS hyper-spectrometer.

ε^2	0.00	0.67	2.00	9.99	36.25	132.80	282.44
G,%	5.95	8.02	9.27	11.25	11.10	8.24	5.23

Table 7. The gain of the adaptive interpolator for the averaging interpolator in the test signal “T-shirts” of “TokyoTech’ hyperspectral dataset.

ε^2	0.00	36.21	818.07	3152.23	6664.50	11060.42	16190.09
G,%	9.49	14.41	7.23	1.70	-1.31	-3.27	-4.87

Table 8. The gain of the adaptive interpolator for the averaging interpolator in the test signal “Moffett Field” of AVIRIS hyper-spectrometer.

ε^2	0.00	0.66	1.99	9.74	34.55	125.98	270.11
G,%	14.49	19.26	21.87	27.52	30.81	28.98	27.40

Table 9. The gain of the adaptive interpolator for the averaging interpolator in the test signal “Urban and Mixed Environment” of SpecTIR hyper-spectrometer.

ε^2	0.00	0.67	2.00	9.94	35.77	131.16	280.30
G,%	7.24	9.44	10.40	11.38	11.90	13.01	12.25

6. Conclusion

We considered the compression of multidimensional signals, which are described by the hypercube, «rotated» in a manner specific for onboard processing. To compress this hypercube, we used the hierarchical compression method. As one of the stages of this method, we used the adaptive interpolation algorithm based on automatic switching between different interpolating functions at each point of the signal. We confirmed computational experiments in natural multidimensional signals, which confirmed that the use of proposed adaptive interpolator allows increasing (up to 31%) the compression ratio of the «rotated» hypercube corresponding to multidimensional hyperspectral signals.

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